A posteriori analysis of Chorin-Temam scheme for Stokes equations
Sébastien Boyaval, M. Picasso

To cite this version:

HAL Id: hal-00876069
https://hal-enpc.archives-ouvertes.fr/hal-00876069
Submitted on 23 Oct 2013

HAL is a multi-disciplinary open access archive for the deposit and dissemination of scientific research documents, whether they are published or not. The documents may come from teaching and research institutions in France or abroad, or from public or private research centers.

L’archive ouverte pluridisciplinaire HAL, est destinée au dépôt et à la diffusion de documents scientifiques de niveau recherche, publiés ou non, émanant des établissements d’enseignement et de recherche français ou étrangers, des laboratoires publics ou privés.
A posteriori analysis of Chorin-Temam scheme for Stokes equations
Analyse a posteriori du schéma Chorin-Temam pour les équations de Stokes

Sébastien Boyaval\textsuperscript{a}, Marco Picasso\textsuperscript{b}

\textsuperscript{a} Université Paris Est, Laboratoire d’hydraulique Saint-Venant (Ecole Nationale des Ponts et Chaussées – EDF R&D – CETMEF), 78401 Chatou Cedex, France ; and INRIA, MICMAC team–project, Rocquencourt, France (sébastien.boyaval@enpc.fr). Corresponding author.

\textsuperscript{b} MATHICSE, Station 8, Ecole Polytechnique Fédérale de Lausanne, 1015 Lausanne, Switzerland (marco.picasso@epfl.ch).

Abstract
We consider Chorin-Temam scheme (the simplest pressure-correction projection method) for the time-discretization of an unstationary Stokes problem in $D \subset \mathbb{R}^d$ ($d = 2, 3$) given $\mu, f$: (P) find $(u, p)$ solution to $u_{|_{t=0}} = u_0, u_{|_{\partial D}} = 0$ and

\[ \frac{\partial u}{\partial t} - \mu \Delta u + \nabla p = f \quad \text{div } u = 0 \quad \text{on } (0, T) \times D. \tag{1} \]

Inspired by the analyses of the Backward Euler scheme performed by C.Bernardi and R.Verfürth, we derive a posteriori estimators for the error on $\nabla u$ in $L^2(0, T; L^2(D))$-norm. Our investigation is supported by numerical experiments.

French version: On discrétise en temps par le schéma Chorin-Temam un problème de Stokes non-stationnaire posé dans $D \subset \mathbb{R}^d$ ($d = 2, 3$) étant donnés $\mu, f$: (P) trouver $(u, p)$ solution de $u_{|_{t=0}} = u_0, u_{|_{\partial D}} = 0$ et (1). En s’inspirant des analyses de C.Bernardi et R.Verfürth pour le schéma Euler rétrograde, nous construisons des estimateurs a posteriori pour l’erreur commise sur $\nabla u$ en norme $L^2(0, T; L^2(D))$. Notre étude est étayée par des expériences numériques.

Keywords: Operator splitting, Pressure correction, Projection method, A posteriori error estimation
French: Séparation d’opérateurs, Correction de pression, Méthode de projection, Estimation d’erreur a posteriori

Version française abrégée
Étant donnés $\mu > 0$, $f \in L^2(0, T; Q^d)$ et $u_0 \in V$ ($Q$ et $V$ sont définis en (2) ci-dessous), on discrétise en temps la formulation faible (P) du problème (P) (équation (4) ci-dessous) par le schéma Chorin-Temam: soit $u^{-1/2} = u_0$, $p^0 = 0$, pour $n = 0, \ldots, N - 1$, étant donnés $\Delta t \in (0, \Delta t]$ et $f^{n+1} = \frac{1}{\Delta t} \int_{t_n}^{t_{n+1}} f(s)ds$ (où $t_0 = \sum_{k=0}^{n-1} \Delta t$; $t_N = T$), (P'): on cherche $u^{n+1/2} \in W$, $p^{n+1} \in Q \cap H^1(D)$ solutions de (5a–5b). La convergence a priori vers des solutions de (P) quand $\Delta t \to 0$ et son ordre sont connus [7, 8, 9] (voir Prop. 1). Mais on aimerait ici estimer $a_{posteriori}$ l’erreur de discrétisation en temps pour bien choisir les pas $\Delta t$ en pratique, ce qui est encore un problème ouvert. Les estimateurs d’erreur a posteriori proposés dans [1, 2] pour la semi-discrétisation en temps avec le schéma Euler rétrograde ne sont pas valables ici. Et les récentes analyses [10, 11] pour la semi-discrétisation en temps avec le schéma Chorin-Temam proposent un estimateur (différent des nôtres) qui ne tient pas compte de tous les termes d’erreur.

Après avoir défini les résidus (10a–10b) d’une approximation Chorin-Temam $u^{NT}$, $p^{NT}$ de la solution du problème (P) construite comme en (7), nous suivons dans ce travail la procédure générique d’analyse a posteriori des équations de Stokes instationnaires qui est présentée dans [2]. Nous testons donc l’équation (11) vérifiée par $e_u = u - u^{NT}$, $e_p = p - p^{NT}$ avec $v = e_u - \Pi e_u \in V$, $q = 0$, où $\Pi$ est un opérateur de projection dans $W$ qui conserve la divergence. De (12) dans $D'(0, T)$, on tire alors l’inégalité (13) avec (8), div $e_u = R_{p_0}$ (9b), div $e_u = -\Pi u^{NT}$, $e_u(0) = 0$, et une intégration par parties. On obtient ensuite une borne supérieure (15) en utilisant par exemple (14a), (14b) selon [2]. D’autre part, on obtient aussi la borne inférieure (18) si en plus de (16) (obtenu facilement avec (10a), (10b) et div $u = 0$) on utilise (17). La procédure d’analyse a posteriori de [2] permet donc bien d’obtenir des bornes supérieures et inférieures complètement calculables de l’erreur $\|\nabla e_u\|_{L^2(0,T;Q^d)} + \|\partial_t e_u + \nabla e_p\|_{L^2(0,T;W)}$ (voir Prop. 2 et Prop. 3). Mais d’une part, il vaut mieux utiliser $\|\text{div } \partial_t u^{NT}\|_{L^2(0,T;Q^d)}$ (plutôt que $\|\text{div } \partial_t u^{NT}\|_{L^2(0,T;Q^d)}$ si on suit strictement [2]).

Preprint submitted to Elsevier October 23, 2013
given
A standard time-discretization of (4) is Chorin-Temam scheme [5, 6]: given

\[ \text{find} \]

We consider a weak formulation of problem (P) find

\[ \text{and because of the regularity assumptions, it also holds} \]

\[ \text{such that} \]

\[ \text{the following equation holds in} \ L^2(0, T) \]

\[ \text{It is well-known that problem (P) is well-posed} [3, 4] \text{(in particular,} \ u \in C([0, T], V) \text{so initial condition makes sense)} \text{and because of the regularity assumptions, it also holds} \]

\[ \text{A standard time-discretization of (4) is Chorin-Temam scheme [5, 6]: given} \]

\[ \text{which yields approximations whose rate of convergence to solutions of (P) is well-known \textit{a priori}} [7, 8, 9]: \]

\[ \text{with} \]

\[ \text{with} \]

\[ \text{with} \]

\[ \text{with} \]

\[ \text{with} \]

\[ \text{with} \]

\[ \text{with} \]

\[ \text{with} \]

\[ \text{with} \]

\[ \text{with} \]

\[ \text{with} \]

\[ \text{with} \]

\[ \text{with} \]

\[ \text{with} \]

\[ \text{with} \]

\[ \text{with} \]

\[ \text{with} \]

\[ \text{with} \]

\[ \text{with} \]

\[ \text{with} \]

\[ \text{with} \]

\[ \text{with} \]

\[ \text{with} \]

\[ \text{with} \]

\[ \text{with} \]

\[ \text{with} \]

\[ \text{with} \]

\[ \text{with} \]

\[ \text{with} \]

\[ \text{with} \]

\[ \text{with} \]

\[ \text{with} \]

\[ \text{with} \]

\[ \text{with} \]

\[ \text{with} \]

\[ \text{with} \]

\[ \text{with} \]

\[ \text{with} \]

\[ \text{with} \]

\[ \text{with} \]

\[ \text{with} \]

\[ \text{with} \]

\[ \text{with} \]

\[ \text{with} \]

\[ \text{with} \]

\[ \text{with} \]

\[ \text{with} \]

\[ \text{with} \]

\[ \text{with} \]

\[ \text{with} \]

\[ \text{with} \]

\[ \text{with} \]

\[ \text{with} \]

\[ \text{with} \]

\[ \text{with} \]

\[ \text{with} \]

\[ \text{with} \]

\[ \text{with} \]

\[ \text{with} \]

\[ \text{with} \]

\[ \text{with} \]

\[ \text{with} \]

\[ \text{with} \]

\[ \text{with} \]

\[ \text{with} \]

\[ \text{with} \]

\[ \text{with} \]

\[ \text{with} \]

\[ \text{with} \]

\[ \text{with} \]

\[ \text{with} \]

\[ \text{with} \]

\[ \text{with} \]

\[ \text{with} \]

\[ \text{with} \]

\[ \text{with} \]

\[ \text{with} \]

\[ \text{with} \]

\[ \text{with} \]

\[ \text{with} \]

\[ \text{with} \]

\[ \text{with} \]

\[ \text{with} \]

\[ \text{with} \]

\[ \text{with} \]

\[ \text{with} \]

\[ \text{with} \]

\[ \text{with} \]

\[ \text{with} \]

\[ \text{with} \]

\[ \text{with} \]

\[ \text{with} \]

\[ \text{with} \]

\[ \text{with} \]

\[ \text{with} \]

\[ \text{with} \]

\[ \text{with} \]

\[ \text{with} \]

\[ \text{with} \]

\[ \text{with} \]

\[ \text{with} \]

\[ \text{with} \]

\[ \text{with} \]

\[ \text{with} \]

\[ \text{with} \]

\[ \text{with} \]

\[ \text{with} \]

\[ \text{with} \]

\[ \text{with} \]

\[ \text{with} \]

\[ \text{with} \]

\[ \text{with} \]

\[ \text{with} \]

\[ \text{with} \]

\[ \text{with} \]

\[ \text{with} \]

\[ \text{with} \]

\[ \text{with} \]

\[ \text{with} \]

\[ \text{with} \]

\[ \text{with} \]

\[ \text{with} \]

\[ \text{with} \]

\[ \text{with} \]

\[ \text{with} \]

\[ \text{with} \]

\[ \text{with} \]

\[ \text{with} \]

\[ \text{with} \]

\[ \text{with} \]

\[ \text{with} \]

\[ \text{with} \]

\[ \text{with} \]

\[ \text{with} \]

\[ \text{with} \]

\[ \text{with} \]

\[ \text{with} \]

\[ \text{with} \]

\[ \text{with} \]

\[ \text{with} \]

\[ \text{with} \]

\[ \text{with} \]

\[ \text{with} \]

\[ \text{with} \]

\[ \text{with} \]

\[ \text{with} \]

\[ \text{with} \]

\[ \text{with} \]

\[ \text{with} \]
Proposition 1. The following estimate holds:
\[
\|u^{\Delta t} - u\|_{L^2(0,T,W)} + \|p^{\Delta t} - p\|_{L^2(0,T,Q^d)} = O(\Delta t^{1\over 2}) \text{ as } \Delta t \to 0 ,
\]  
(6)
where \(u^{\Delta t}\) and \(p^{\Delta t}\) are defined as
\[
u^{\Delta t}(t) = \frac{t - t_n}{\Delta t} u^{n+1/2} - \frac{t - t_{n+1}}{\Delta t} u^{n-1/2} , \quad p^{\Delta t}(t) = p^* . \quad \forall t \in (t_n, t_{n+1}] ,
\]  
(7)

In this work, we would like to numerically evaluate a posteriori the time discretization error with a view to adequately choosing the time steps \(\Delta t\) of Chorin-Temam scheme in practice (under a given error tolerance), which is still an open problem. A posteriori error estimations have been proposed for the Backward-Euler scheme (including full discretizations, in time and space) \([1, 2]\) but they do not straightforwardly apply here. And a posteriori analyses of Chorin-Temam scheme have indeed been carried out recently \([10, 11]\) but they suggest an estimator (different than ours) that does not account for the whole error. The present investigation focuses on fully computable error bounds for Chorin-Temam scheme derived from the generic a posteriori framework introduced in \([2]\) for the unstationary Stokes equations. Although our estimator is a priori not fully efficient, it is better than other ones and useful in some cases.

Note that in the following, we denote by \(a \lesssim b\) any relation \(a \leq Cb\) between two real numbers \(a, b\) where \(C > 0\) is a numerical constant independent of the data of the problem. Moreover, we shall use standard inequalities such as
\[
\|\text{div } v\|_Q \leq d^{1/2} \|\nabla v\|_{Q^{1/2}} , \quad \forall v \in W
\]
and Poincaré-Friedrichs inequality with constant \(C_p(Q) > 0\), then also
\[
\max(\|v\|_{Q^{1/2}}, \|\nabla v\|_{Q^{1/2}}) \leq \|v\|_W \leq (1 + C_p^2) \|\nabla v\|_{Q^{1/2}} , \quad \forall v \in W .
\]  
(8)

In Section 2, we derive a posteriori error estimates following the procedure of \([2]\), i.e. invoking \(\Pi : W \to W\), a projection such that \(v - \Pi v \in V\). For all \(v \in W, \Pi v\) is the solution of Stokes equations: \(\exists q_v \in \bar{Q}, \forall T (\partial T) > 0\) such that
\[
(\nabla \Pi v, \nabla w) = (q_v, \text{div } w) \quad (r, \text{div } \Pi v) = (r, \text{div } v) , \quad \forall (w, r) \in W \times \bar{Q} ,
\]  
(9a)
\[
T||\nabla \Pi v||_Q \leq \|\text{div } v\|_Q .
\]  
(9b)

In Section 3, we numerically test our a posteriori estimator.

2. A posteriori estimation of semi-discrete errors

Let us define residuals for Chorin-Temam approximations \(u^{\Delta t}, p^{\Delta t}\) as in \((7)\) of the solution to the problem \((P)\)
\[
< R_u, v >_{W^*, W} = (f, v) - (\partial_t u^{\Delta t}, v) - (\nabla p^{\Delta t}, v) - \mu(\nabla u^{\Delta t}, \nabla v) \equiv (f - f^{\Delta t}, v) + \mu(\nabla u^{\Delta t}, \nabla v) , \quad \forall v \in W ,
\]  
(10a)
\[
(R_p, q) = -(\text{div } u^{\Delta t}, q) , \quad \forall q \in Q ,
\]  
(10b)
where \(f^{\Delta t} = f^{n+1}, \ u^{\Delta t, n+1} = u^{n + 1\over 2}\) for \(t \in (t_n, t_{n+1}]\). The errors \(e_u = u - u^{\Delta t}, e_p = p - p^{\Delta t}\) satisfy:
\[
(\partial_t e_u + \nabla e_p, v) + \mu(\nabla e_u, \nabla v) + (\text{div } e_u, q) = < R_u, v >_{W^*, W} + (R_p, q) , \quad \forall (v, q) \in W \times Q .
\]  
(11)

Testing \((11)\) against \(v = e_u - \Pi e_u \in V, q = 0\), yields in \(\mathcal{D}'(0,T)\) (distributional sense)
\[
\frac{1}{2} \frac{d}{dt} \|e_u\|_Q^2 + \mu \|\nabla e_u\|_{Q^{1/2}}^2 = < R_u, e_u >_{W^*, W} - < R_u, \Pi e_u >_{W^*, W} + (\partial_t e_u, \Pi e_u) + \mu(\nabla e_u, \nabla \Pi e_u) .
\]  
(12)

Using Young inequality with \((8), \text{div } e_u = R_p, \ (9b), \Pi e_u = -\Pi u^{\Delta t}, e_u(0) = 0, \text{ and integrating by part, one obtains}
\[
\|e_u\|_{L^2(0,T,W)}^2 + \mu \|\nabla e_u\|_{L^2(0,T,Q^{1/2})}^2 \lesssim \|R_u\|_{L^2(0,T,W)}^2 + \mu \|R_p\|_{L^2(0,T,Q)}^2 + \int_0^T \| (e_u, \partial_t \Pi e_u) + \| (e_u, \Pi e_u) \|_{L^2(0,T)} .
\]  
(13)
If we follow [2], then (13) yields a computable upper-bound using the following inequalities with Young’s one

\[
\int_0^T |(e_u, \partial_t \Pi u^{\Delta t})| \leq \|e_u\|_{L^2(0,T;Q')} \|\Pi\partial_t u^{\Delta t}\|_{L^1(0,T;Q')} \tag{14a}
\]

\[
\|e_u, \Pi u^{\Delta t}\|_{L^2(0,T;\Omega)} \lesssim \|e_u\|_{L^2(0,T;Q')} \|\div u^{\Delta t}\|_{L^2(0,T;Q')} \ . \tag{14b}
\]

Since \(\|\partial_t e_u + \nabla e_p\|_{L^2(0,T;W')} \leq 2\|R_u\|_{L^2(0,T;W')} + 2\|\nabla e_u\|_{L^2(0,T;Q')}\) also holds from (10a), one indeed obtains from (9b):

**Proposition 2.** There exists a constant \(c^*(D) > 0\) such that the following computable estimations hold

\[
\frac{1}{c^*} \max \left( \|e_u\|_{L^2(0,T;Q')}, \|\partial_t e_u + \nabla e_p\|_{L^2(0,T;W')}, \|\Pi e_u\|_{L^2(0,T;Q')} \right) \leq \|f - f^{\Delta t}\|_{L^2(0,T;Q')} + \mu \|\nabla u^{\Delta t} - \nabla u^{\Delta t}\|_{L^2(0,T;Q')} + \mu \|\div u^{\Delta t}\|_{L^2(0,T;Q')} + \|\div \partial_t u^{\Delta t}\|_{L^2(0,T;Q')} \tag{15}
\]

On the other hand, from (10a), (10b) and \(\div u = 0\), one has

\[
\mu \|\nabla u^{\Delta t} - \nabla u^{\Delta t}\|_{L^2(0,T;Q')} \lesssim \|f - f^{\Delta t}\|_{L^2(0,T;Q')} + \|\partial_t e_u + \nabla e_p\|_{L^2(0,T;W')} + \mu \|\nabla e_u\|_{L^2(0,T;Q')} \ . \tag{16}
\]

from which one next straightforwardly obtains the counterpart of (15) if one uses, in addition to (16),

\[
\|\div \partial_t u^{\Delta t}\|_{L^2(0,T;Q')} \lesssim \frac{T}{\min_{n=0}^{N-1} |\Delta n|} \|\nabla e_u\|_{L^2(0,T;Q')} \ . \tag{17}
\]

**Proposition 3.** There exists a constant \(c^*(D) > 0\) such that the following computable lower bound holds

\[
c^* \left( \mu \|\nabla u^{\Delta t} - \nabla u^{\Delta t}\|_{L^2(0,T;Q')} + \mu \|\div u^{\Delta t}\|_{L^2(0,T;Q')} + \frac{1}{N} \|\div \partial_t u^{\Delta t}\|_{L^2(0,T;Q')} \right) \leq \|f - f^{\Delta t}\|_{L^2(0,T;Q')} + \|\partial_t e_u + \nabla e_p\|_{L^2(0,T;W')} + \left( \mu + \frac{1}{\min_{n=0}^{N-1} |\Delta n|} \right) \|\nabla e_u\|_{L^2(0,T;Q')} \ . \tag{18}
\]

**Proof of (17).** We use the following inequality with \(\div u = 0\), noting \(\frac{1}{\Delta n} \int_N^{N+1} \|\nabla u^{\Delta t}\|_Q^2 \geq \|u^{\Delta t+\frac{1}{2}}\|_Q^2 + \|u^{\Delta t-\frac{1}{2}}\|_Q^2\):

\[
\|\div \partial_t u^{\Delta t}\|_{L^2(0,T;Q')} \leq N \sum_{n=0}^{N-1} \|\div (u^{\Delta t+\frac{1}{2}} - u^{\Delta t-\frac{1}{2}})\|_Q^2 \leq 2N \sum_{n=0}^{N-1} \|\div u^{\Delta t+\frac{1}{2}}\|_Q^2 + \|\div u^{\Delta t-\frac{1}{2}}\|_Q^2 \leq \frac{12N}{\Delta n} \int_0^T \|\div u^{\Delta t}\|_Q^2 \ . \tag{19}
\]

So the framework introduced in [2] for an a posteriori analysis of a Backward Euler discretization of Stokes problem still applies here with Chorin-Temam scheme (it applies with any scheme provided the reconstructions \(u^{\Delta t}, p^{\Delta t}\) are defined using appropriate discrete variables). Though, the point is now to let not only the residuals, but also the two last terms in (13), be easily and sharply estimated (contrary to the fully discrete Backward Euler case in [2], these terms cannot be neglected here because they can be of the same order as the error). We draw the following conclusions. First, Prop. 2 and 3 suggest that the procedure of [2] should be modified here to estimate the error

\[
\mu \|\nabla e_u\|_{L^2(0,T;Q')} + \|\partial_t e_u + \nabla e_p\|_{L^2(0,T;W')} \tag{19}
\]

a posteriori in a more robust way than by the estimator (20) obtained straightforwardly from the estimations above:

\[
\mu \|\nabla u^{\Delta t} - \nabla u^{\Delta t}\|_{L^2(0,T;Q')} + \mu \|\div u^{\Delta t}\|_{L^2(0,T;Q')} + \|\div \partial_t u^{\Delta t}\|_{L^2(0,T;Q')} \ . \tag{20}
\]

\(^1\)Observe that the convergence of \(\partial_t u^{\Delta t} + \nabla p^{\Delta t}\) to \(\partial_t u + \nabla p\) in \(L^2(0, T; W')\) is natural here, like for Backward-Euler schemes [1].
For instance, if one replaces (14a) with the following upper bound (21), on noting (8) and (9b),
\[ \int_0^t [e_n, \partial_t \Pi e_n] \lesssim \| \nabla e_n \|_{L^2(0,T;Q)} \| \text{div} \, \partial_t u^\Delta \|_{L^2(0,T;Q)}, \tag{21} \]
then bounds similar to (15) and (18) hold but with \( \| \text{div} \, \partial_t u^\Delta \|_{L^2(0,T;Q)} \) instead of \( \| \text{div} \, \partial_t u^\Delta \|_{L^2(0,T;Q)} \) and without invoking discretization parameters like \( N \) and \( \Delta t \), which suggests the a posteriori error estimator (22) more robust than (20):
\[ \mu \| \nabla u^{\Delta t} - \nabla u^\Delta \|_{L^2(0,T;Q)}^2 + \mu \| \text{div} \, u^\Delta \|_{L^2(0,T;Q)}^2 + \| \text{div} \, \partial_t u^\Delta \|_{L^2(0,T;Q)}^2. \tag{22} \]

Of course, this is not a fully efficient estimator yet, since it is a priori not bounded above and below by the error (19), even if one neglects the source error \( \| f - f^M \|_{L^2(0,T;Q)} \) of “high” order \( O(\Delta t^2) \) – recall (6) –. It is nevertheless useful in some cases, as shown in the next section. Second, (22) sometimes improves some estimators in the literature like
\[ \mu \| \nabla u^{\Delta t} - \nabla u^\Delta \|_{L^2(0,T;Q)}^2 + \sum_{n=0}^{N-1} \| \Delta t^{n+1} \nabla p^{n+1} - \Delta t^n \nabla p^n \|_{L^2(T)}^2 \tag{23} \]
that was proposed in [10, 11]. Clearly, for small \( \Delta t \), our estimator is larger than the one proposed in [10, 11], on noting
\[ \| \Delta t^{n+1} \nabla p^{n+1} - \Delta t^n \nabla p^n \|_{L^2(T)}^2 \lesssim \| \text{div} \, u^{n+1/2} - \text{div} \, u^{n-1/2} \|_{L^2(T)}^2 \lesssim \Delta t \| \text{div} \, \partial_t u^\Delta \|_{L^2(T)}^2 \]
for \( t \in (t_n, t_{n+1}] \), after using a Poincaré inequality with (5b). And, the numerical example of the following Section 3 indeed shows that (22) is a better upper-bound than (23), at least when the error is not mainly driven by \( \| \text{div} \, u^\Delta \|_{L^2(T)}^2 \).

3. Numerical results

We want to bring numerical evidences that estimator (22) is sometimes i) useful and ii) better than (20) and (23). Given \( \lambda > 0 \), we numerically compute the efficiencies of the three estimators using discrete approximations of
\[ u = \pi \sin(\lambda t) \left( \sin(2\pi x) \sin(2\pi y) \right), \quad p = \pi \sin(\lambda t) \cos(\pi x) \sin(\pi y) \]
in \( \mathcal{D} \equiv (-1,1) \times (-1,1) \) (\( d = 2 \)), with \( t \in (0,T) \) uniformly discretized by time steps \( \Delta t = T/N \) (\( N \in \mathbb{N} \)) when \( \mu = 1 \).

We discretize in space the velocity components and the pressure with, respectively, continuous \( P_2 \) and \( P_1 \) Finite-Elements functions, i.e. in conforming discrete spaces \( W_h \subset W \) and \( \mathcal{Q}_h \subset (Q \cap H^1(\mathcal{D})) \) defined on regular simplicial meshes of \( \mathcal{D} \). The a posteriori analysis of Section 2 still applies with right-hand side in (13) defined using now fully-discrete approximations. Then indeed, following [2], one can decompose the fully-discrete residuals in a sum of two terms, one accounting for space-discretization errors and one for time-discretization errors. The two last terms in the (new) right-hand side of (13) remain the same (they are explicitly computable). This yields estimators linked to the time discretization which are exactly the space-discrete counterparts of the terms in the bounds (15) and (18). Moreover, in our numerical example, space discretization errors prove negligible in comparison with time discretization errors (as already observed in [12] for \( \lambda = 1 \)). We thus next show only numerical results obtained for one sufficiently fine mesh (with more than \( 10^5 \) vertices).

We compare the effectiveness of (space-discrete versions of) the a posteriori error estimators (20), (22) and (23) evoked in the previous section for the (space-discrete) error \( \| \nabla e_n \|_{L^2(0,T;Q)}^2 + \| \partial_t e_n + \nabla e_n \|_{L^2(0,T;W)}^2 \). One clearly sees from the numerical results obtained for \( \lambda = 10, T \leq 3 \) in Fig. 1 that i) (20) is not robust when \( \Delta t \) is too small or \( T \) too large compared with (22), and ii) (22) is better than the estimator (23) in so far as, for that specific case, it has the same decay rate than the error (19) and not a faster one like (23). Though, our estimator (22) is still not fully efficient, even when adding the term \( \| \text{div} \, u^\Delta \|_{L^2(0,T;Q)}^2 \) to (22), since it is not bounded above and below by the error. Furthermore, if we use it as such (that is as a sum of terms without coefficients), in some cases, it also fails (like (23)) at evaluating correctly the error. For instance when \( \lambda = 1 \), the error (19) scales like \( \| \text{div} \, u^\Delta \|_{L^2(0,T;Q)}^2 \) with respect to \( \Delta t \), while the other terms in (22) are of higher-order in \( \Delta t \). But this cannot be observed unless \( \Delta t \) is very small, even if we use (22) plus \( \| \text{div} \, u^\Delta \|_{L^2(0,T;Q)}^2 \) as an estimator2 insofar as the magnitude of the latter term is much smaller than the

---

2Note that in fact we also added the term \( \| \text{div} \, u^\Delta \|_{L^2(0,T;Q)}^2 \) to (20), (22) and (23) in Fig. 1, but it is small compared to other terms, thus unseen.
Figure 1: For $\Delta t = .1, .05, .025, .0125, .00625$, effectiveness in log scale (as a function of $T$) of (20) – top left –, (22) – top right –, and (23) – bottom left – ($\|\text{div } u^\Delta\|_{L^\infty(0,T,Q)}$ included) at estimating (19) when $\lambda = 10, T \leq 3$; and $\|\text{div } u^\Delta\|_{L^\infty(0,T,Q)}^2$ error (19) – bottom right – when $\lambda = 1, T \leq 10$.

former ($10^{-1}$ vs. $10^2$). Then, for too large $\Delta t$, the effectivity of our estimator also decays, and the error still cannot be evaluated confidently. So, without even mentioning the error $\|e_u\|_{L^\infty(0,T,Q)}$, the question how to estimate a posteriori error discretizations in Chorin-Temam scheme efficiently and robustly (in all cases) thus remains open. One should at least coefficient adequately the terms in the estimator above (22) plus $\|\text{div } u^\Delta\|_{L^\infty(0,T,Q)}^2$. We nevertheless hope to have shed new light on the problem.

References