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To cite this version:

Pierre Moulon, Bruno Duisit, Pascal Monasse. Global Multiple-View Color Consistency. CVMP, Nov 2013, Londres, United Kingdom. 2013. <hal-00873517>

HAL Id: hal-00873517

https://hal-enpc.archives-ouvertes.fr/hal-00873517

Submitted on 15 Oct 2013

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Global Multiple-View Color Consistency

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1 Introduction

In a multiple-view image acquisition process, color consistency is not ensured. This is an important problem for image fusion tasks: object texturing or mosaics blending for example. In automatic mode, the camera adapts its settings –shutter-speed and aperture– to the captured image content. Therefore the color of objects changes over an image sequence. In order to restore the color consistency, a transformation model between reference and observed colors have to be estimated. It introduces two main problems: the data selection (common pixels between images) and the estimation of a reliable color transformation between those pixels. While most techniques ensure only pairwise consistency [HaCohen et al. 2011; Reinhard et al. 2001] and possibly proceed incrementally [Snavely et al. 2008], we address the problem globally on the entire photo collection.

We propose a global multi-view color consistency solution that in a first step selects robustly the common color information between images and in a second step estimates the color transformations for the captured image content. Therefore the color of objects changes. Pixel by pixel alignment is not guaranteed, so we use histogram as pixel masks, common but unadjusted pixel colors are extracted. Virtual segments between pairs of images. Using common segments we use the VLD filter [Liu and Marlet 2012] that identifies common epipolar geometry is performed. To extend this correspondence set, finding techniques, such as SIFT keypoints, and an estimation of the geometrically coherent points are identified by local image matching method for reliable feature correspondence. In automatic mode, the camera adapts its settings –shutter-speed and aperture– to the captured image content. Therefore the color of objects changes over an image sequence. In order to restore the color consistency, a transformation model is used between reference and observed colors. In automatic mode, the camera adapts its settings –shutter-speed and aperture– to the captured image content.

Notice that we do not use the whole set of common pixel colors but only quantiles of histograms. This ensures scalability of our solution. Also, our solution to register a series of color histograms is global and results in optimizing a convex problem based on histogram quantiles. In the experiment of Figure 1 we use 10 quantiles per histogram, with no noticeable difference when taking more.

2 Our approach

In a sequence of images $I_i, i = 1, \ldots, n$, we aim at having corresponding pixel colors as consistent as possible. We begin by computing the common plausible corresponding pixels per image pair. Geometrically coherent points are identified by local image matching techniques, such as SIFT keypoints, and an estimation of the epipolar geometry is performed. To extend this correspondence set, we use the VLD filter [Liu and Marlet 2012] that identifies common virtual segments between pairs of images. Using common segments as pixel masks, common but unadjusted pixel colors are extracted. Pixel by pixel alignment is not guaranteed, so we use histogram distribution of colors. Color consistency is solved by best aligning a set of quantile positions of the cumulated histogram distribution under the $l_\infty$ norm. A gain $g_i$ and offset $o_i$ is used per image to normalize the shutter speed and the aperture time. This is applied for each color channel independently to build a look up table and align the colors. We solve the following Linear Programming problem:

$$\minimize_{g_i, o_i} \sum_{i,j} \left| (g_i Q_{jk}^i + o_i) - (g_j Q_{jk}^j + o_j) \right|$$

subject to $g_i \geq 0 : \forall i$, $\text{ref} = 1$ and $\text{offset} = 0$,

where $Q_{jk}^i$ corresponds to the $k$th quantile of the histogram of common pixels of image $i$ with image $j$, and ref is the index of a chosen color reference image.

References


